## Homework 5

Due: Friday, 4 March, 2016.

**Practice:** Questions marked with a  $\sqrt{}$  in Sections Three.II.1–2 from the textbook.

- 1. [12 marks] Determine whether the following are linear transformations.
  - (a) A translation  $T : \mathbb{R}^2 \to \mathbb{R}^2$  given by  $T(\mathbf{v}) = \mathbf{v} + \mathbf{a}$ , where  $\mathbf{a} \in \mathbb{R}^2$  is a non-zero vector.
  - (b) The map  $T: \mathcal{P}_2 \to \mathcal{P}_3$  given by  $T(a + bx + cx^2) = ax + \frac{b}{2}x^2 + \frac{c}{3}x^3$ .
- 2. [16 marks] For each of the following linear maps  $T : \mathbb{R}^2 \to \mathbb{R}^2$ , find  $T(\mathbf{e}_1)$  and  $T(\mathbf{e}_2)$  where  $\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $\mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ . Write down the matrix representing T (with respect to the standard

bases). Draw a neat diagram of the image of the unit square  $\begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 \mid 0 \le x, y \le 1 \}$ under the given transformation, with  $T(\mathbf{e}_1)$  and  $T(\mathbf{e}_2)$  clearly labelled.

- (a)  $T_1$  is a reflection in the line y = x.
- (b)  $T_2$  is a reflection in the *y*-axis.
- (c)  $T_3$  is an anticlockwise rotation about the origin through an angle of  $\frac{\pi}{2}$ .
- (d)  $T_4 = T_2 \circ T_1$ , the map defined by applying  $T_1$  followed by  $T_2$ .

What can you say about  $T_3$  and  $T_4$ ? Would  $T_1 \circ T_2$  define the same map as  $T_2 \circ T_1$ ?

- **3.** [12 marks] Let  $T : V \to W$  be a linear transformation. Recall that the *kernel* of T is  $\ker T = \{ \mathbf{v} \in V \mid T(\mathbf{v}) = \mathbf{0}_W \}.$ 
  - (a) Given  $\mathbf{v}_1, \mathbf{v}_2 \in V$ , prove that  $T(\mathbf{v}_1) = T(\mathbf{v}_2)$  if and only if  $\mathbf{v}_1 \mathbf{v}_2 \in \ker T$ .
  - (b) Let  $\mathbf{w} \in W$ . Show that the set of all  $\mathbf{v} \in V$  satisfying the equation  $T(\mathbf{v}) = \mathbf{w}$  is either empty, or is of the form

 $\{\mathbf{p} + \mathbf{h} \mid \mathbf{h} \in \ker T\}$ 

where  $\mathbf{p} \in V$  is any vector satisfying  $T(\mathbf{p}) = \mathbf{w}$ . (In fact, the set is non-empty if and only if  $\mathbf{w} \in \operatorname{im} T$ .)