

Miscellaneous Expressions and Results

- **Second Derivative Test.** Test depends on sign of D and of f_{xx} .

$$D = (f_{xx})(f_{yy}) - (f_{xy})^2$$

- **Polar Coordinates.** $x = r \cos(\theta)$; $y = r \sin(\theta)$

$$dA = r dr d\theta$$

- **Cylindrical Coordinates.** $x = r \cos(\theta)$; $y = r \sin(\theta)$; $z = z$

$$dV = r dr d\theta dz$$

- **Spherical Coordinates.** $x = \rho \sin(\phi) \cos(\theta)$; $y = \rho \sin(\phi) \sin(\theta)$; $z = \rho \cos(\phi)$

$$dV = \rho^2 \sin(\phi) d\rho d\phi d\theta$$

- **General Coordinates in 2-d.**

$$dA = \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

where

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix}$$

- **General Coordinates in 3-d.**

$$dV = \left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| du dv dw$$

where

$$\frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{vmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{vmatrix}$$

- **Surface Area.** Area element of the portion of the graph $z = f(x, y)$ which lies over the rectangle $dxdy$

$$dA = \sqrt{1 + f_x^2 + f_y^2} dxdy$$

- **Fundamental Theorem:**

$$\int_C (\nabla f) \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$$

where the curve C is the curve given by $\mathbf{r}(t)$ where $a \leq t \leq b$.

- **Green's Theorem:** $\mathbf{F} = \langle P, Q \rangle$ is a vector field.

$$\oint_C P dx + Q dy = \iint_D (Q_x - P_y) dA$$

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_D \text{curl}(\mathbf{F}) \cdot \hat{\mathbf{k}} dA$$

where C is the positively oriented boundary of the 2-dimensional region D .

- **Stokes' Theorem:** $\mathbf{F} = \langle P, Q, R \rangle$ is a vector field.

$$\oint_{\partial S} \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl}(\mathbf{F}) \cdot d\mathbf{S}$$

where ∂S is the positively oriented boundary of the oriented surface S in 3-dimensional space.

- **Divergence Theorem:** $\mathbf{F} = \langle P, Q, R \rangle$ is a vector field.

$$\oiint_{\partial E} \mathbf{F} \cdot d\mathbf{S} = \iiint_E \text{div}(\mathbf{F}) dV$$

where ∂E is the positively oriented boundary of the 3-dimensional region E .

- **Surface area elements:**

$$d\mathbf{S} = \frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v} du dv$$

and

$$dS = \left| \frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v} \right| du dv$$

where the surface has parametric description $\mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$.

- **Vector differential operator:**

$$\nabla = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle$$

can operate on functions (grad), and on vector fields either like a dot product (div) or like a cross product (curl).