

Nabla: The vector differential operator ∇ is pronounced *nabla*, and is defined to be

$$\nabla = \frac{\partial}{\partial x} \hat{\mathbf{i}} + \frac{\partial}{\partial y} \hat{\mathbf{j}} + \frac{\partial}{\partial z} \hat{\mathbf{k}}$$

Grad: ∇ can act on a function (scalar field) f to give a vector field called the *gradient of f* .

$$\nabla f = \frac{\partial f}{\partial x} \hat{\mathbf{i}} + \frac{\partial f}{\partial y} \hat{\mathbf{j}} + \frac{\partial f}{\partial z} \hat{\mathbf{k}} = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right\rangle$$

Recall that ∇f is always perpendicular to the level surfaces of f , points in the direction of maximum rate of increase of f , and that $|\nabla f|$ is this maximum rate of increase.

Div: The operator ∇ can act on a vector field \mathbf{F} in the same way as a dot product. This gives us a scalar field (or function) called the *divergence of \mathbf{F}* which is defined by

$$\operatorname{div} \mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

where $\mathbf{F} = \langle P, Q, R \rangle$.

Curl: The operator ∇ can act on a vector field \mathbf{F} in the same way as a cross product. This gives another vector field called the *curl of \mathbf{F}* which is defined by

$$\operatorname{curl} \mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} = \langle R_y - Q_z, P_z - R_x, Q_x - P_y \rangle$$

Laplace operator: The Laplace operator acts on a scalar field or function and is defined to be *div grad*

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

Two interpretations of Green's Theorem: The two equations below are versions of Green's theorem. They help us gain an intuitive understanding of *div* and *curl*.

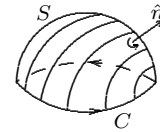
$$\int_C (\mathbf{F} \cdot \hat{\mathbf{T}}) ds = \int_C \mathbf{F} \cdot d\mathbf{r} = \int \int_D \operatorname{curl}(\mathbf{F}) \cdot \hat{\mathbf{k}} dA \quad \text{Tangential components,}$$

and

$$\int_C (\mathbf{F} \cdot \hat{\mathbf{n}}) ds = \int \int_D \operatorname{div}(\mathbf{F}) dA \quad \text{Normal components.}$$

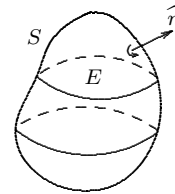
Stokes Theorem: Let S be an oriented, piecewise-smooth surface bounded by a positively oriented, simple, closed, piecewise-smooth curve C . Let \mathbf{F} be a vector field whose components have continuous partial derivatives on an open region of \mathbf{R}^3 which contains S . Then

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl}(\mathbf{F}) \cdot d\mathbf{s}$$



Divergence Theorem: Let E be a simple solid region in \mathbf{R}^3 whose boundary surface S has a positive (outward) orientation. Let \mathbf{F} be a vector field whose components have continuous partial derivatives on an open region of \mathbf{R}^3 which contains E . Then

$$\iint_S \mathbf{F} \cdot d\mathbf{s} = \iiint_E \text{div}(\mathbf{F}) dv$$



Physical Interpretations: Let \mathbf{F} be the velocity vector field of a fluid flow. Let $P_0 = (x_0, y_0, z_0)$ be a point in the fluid flow, and \mathbf{n} be a unit vector based at P_0 . Then

$$\text{curl}(\mathbf{F})(P_0) \cdot \mathbf{n}$$

measures the rotating effect of the fluid about the axis \mathbf{n} . This rotating effect is greatest about an axis which points in the direction of $\text{curl}(\mathbf{F})(P_0)$.

Also $\text{div}(\mathbf{F})(P_0)$ measures the net rate of outward flux per unit volume at P_0 .