# Conformal Curvature Flows on $S^1$ and Image Processing

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## Outline

Setup of the question: introducing curvatures and curvature flow equations.

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Application in image processing.

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is a conformal covariant, namely for any  $g_1 \in [g]$ , writing  $g_1 = \varphi^{\frac{4}{n-2}}g$  with  $\varphi > 0$ , we have

$$L_{g_1}u = L_{\varphi^{\frac{4}{n-2}}g}u = \varphi^{-\frac{n+2}{n-2}}L_g(\varphi u).$$

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**Ex**istence of extremal metrics? Parabolic approach?

**Gl**obal existences and convergence of the flows?

Let  $(S^1, g_s)$  be the unit circle with standard metric  $g_s = d\theta \otimes d\theta$ . For any metric g on  $S^1$ , we write  $g := d\sigma \otimes d\sigma = v^{-4}g_s$  for some positive function v and define a general  $\alpha$ -curvature of g for any positive constant  $\alpha$  by

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where  $\Delta_g = D_{\sigma\sigma}$ .  $L_g^{\alpha}$  is a conformal covariant: **Proposition:** For  $\varphi > 0$ , if  $g_2 = \varphi^{-4}g_1$  then  $R_{g_2}^{\alpha} = \varphi^3 L_{g_1}^{\alpha} \varphi$ , and

$$L^{\alpha}_{g_2}(\psi) = \varphi^3 L^{\alpha}_{g_1}(\psi\varphi), \quad \forall \psi \in C^2(\mathbf{S^1}).$$

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Existence of an extremal metric in the same class by deformation? Parabolic approach: Introduce  $\alpha$ -curvature flow as

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$$\partial_t \overline{R_g^{\alpha}} = \frac{1}{4\pi} \int (R_g^{\alpha} - \overline{R_g^{\alpha}})^2 d\sigma.$$

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Will see shortly

$$\overline{R_g^{\alpha}} \le 1.$$

for some special  $\alpha$ .

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Case of  $\alpha = 1$ . The affine curvature of a closed strictly convex curve = its 1-curvature:  $\mathbf{x}(\theta) \subset \mathbf{R}^2$  ( $\theta \in [0, 2\pi]$ ) be such a curve, parameterized by the angle  $\theta$  between the tangent line and x-axis. The affine arc-length function  $\sigma(\theta) = \int_0^{\theta} k^{-2/3} d\theta$ , where  $k = k(\theta)$  is the curvature. Then the affine curvature of  $\mathbf{x}(\theta)$  is given by:

$$\kappa = k((k^{\frac{1}{3}})_{\theta\theta} + k^{\frac{1}{3}}) = (k^{\frac{1}{3}})^3((k^{\frac{1}{3}})_{\theta\theta} + k^{\frac{1}{3}}).$$

It coincides with 1-curvature  $R_{g_x}^1$ , where  $g_x = (k^{\frac{1}{3}})^{-4} d\theta \otimes d\theta$ .

#### **Affine curvature =1-curvature**

One the other hand, given  $(S^1, g)$ , write  $g = u^{-4}g_s$ . Suppose  $u(\theta)$  satisfies the orthogonal condition:

$$\int_{0}^{2\pi} \frac{\cos\theta}{u^{3}(\theta)} d\theta = \int_{0}^{2\pi} \frac{\sin\theta}{u^{3}(\theta)} d\theta = 0.$$
(3)

Define  $\mathbf{x}(\theta)$  as

$$\mathbf{x}(\theta) = \left(\int_0^\theta \frac{\cos\theta}{u^3(\theta)} d\theta, \int_0^\theta \frac{\sin\theta}{u^3(\theta)} d\theta\right).$$

Then  $\mathbf{x}(\theta)$  is a closed strictly convex curve, and its affine curvature is equal to  $R_g^1$ .

Therefore we have the following correspondece:

 $\begin{bmatrix} \text{Close convex curve } \mathbf{x}(\theta) \\ \text{with curvature } k(\theta). \\ \text{Affine curvature } \kappa(\theta) \end{bmatrix} \leftrightarrow \begin{bmatrix} \text{Metric } g = (k^{\frac{1}{3}})^{-4}g_s \text{ on } S^1 \\ \text{with } v = k^{\frac{1}{3}} \text{ satisfies } (3). \\ 1 \text{-curvature } R_g^1 \end{bmatrix}$ 

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 $\alpha = 4$ : The 4-curvature  $R_g^4$  can be viewed as the scalar curvature in an analogous one-dimensional Yamabe flow.

NOW: flow method to find the extremal metrics for the cases  $\alpha = 1$ and  $\alpha = 4$ . We denote  $R_q^1$  by  $\kappa$ . An analytic proof to the following general Blaschke-Santaló type inequality, which implies that  $\overline{\kappa}_g$  is bounded above, and classifies all the extremal metrics:

General Blaschke-Santaló inequality For  $u(\theta) \in H^1(S^1)$  and u > 0, if u satisfies the orthogonal condition (3), then

$$\int_{0}^{2\pi} (u^2 - u_{\theta}^2) d\theta \int_{0}^{2\pi} u^{-2}(\theta) d\theta \le 4\pi^2,$$

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and the equality holds if and only if

$$u(\theta) = c\sqrt{\lambda^2 \cos^2(\theta - \alpha) + \lambda^{-2} \sin^2(\theta - \alpha)}.$$

## **Exponential convergence**

**Theorem:** Suppose  $g_0 = u^{-4}(\theta, 0)g_s$  and  $u(\theta, 0)$  satisfies the *orthogonal condition (3).* Then there is a unique smooth solution to the flow equation

$$\partial_t g = (\overline{\kappa} - \kappa)g, \quad g(\theta, 0) = g_0(\theta)$$

for  $t \in [0, +\infty)$ . Moreover,  $g(t) \to g_{\infty}$  exponentially as  $t \to +\infty$ , and the 1-curvature of  $g_{\infty}$  is constant.

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Our 1-curvature flow  $\Leftrightarrow$  The normalized affine curve-shortening flow,

$$\mathbf{x}_t(\sigma, t) = \mathbf{x}_{\sigma\sigma}.$$

## **Outline of the proof**

Along the flow  $\partial_t g = (\overline{\kappa}_g - \kappa_g)g$ , we have

$$\kappa_t = \frac{1}{4}\Delta\kappa + \kappa(\kappa - \overline{\kappa}), \quad u_t = \frac{1}{4}(\kappa - \overline{\kappa})u,$$

i.e.

$$u_{t} = \frac{1}{4}u^{4}\Delta_{g_{s}}u + \frac{1}{4}u^{5} - \frac{1}{4}\overline{\kappa}u.$$

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Therefore

$$\partial_t \int d\sigma = \partial_t \int u^{-2} d\theta = \int \frac{1}{2} (\overline{\kappa} - \kappa) d\sigma = 0,$$

$$\partial_t \int_0^{2\pi} u^{-3}(\theta) \cos \theta d\theta = \frac{3\overline{\kappa}}{4} \int_0^{2\pi} u^{-3}(\theta) \cos \theta d\theta.$$

It preserves the length and the orthogonality!

## **Existence of the flow**

Suppose g(t) satisfies the flow equation on [0, T], then we have

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It follows from the maximum principle that

 $\kappa \ge \min \kappa(\sigma, 0) e^{-\int_0^t \overline{\kappa} d\tau},$ 

then:  $u(\sigma, t) = u(\sigma, 0) \cdot e^{\frac{1}{4} \int_0^t (\kappa - \overline{\kappa}) d\tau} \ge \tilde{c}_2(\kappa(\sigma, 0), t_0) > 0.$ 

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Using the evolution equation of u and the orthogonal condition, we can prove that there exist C = C(T) such that  $\frac{1}{C} \le u \le C$ . Therefore, from standard parabolic estimates that the solution exists for all  $t \in [0, \infty)$ .

## **Convergence of the flow**

For  $p \geq 2$ , we define

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Direct computation yields

$$\partial_t F_p \le C_1(p)(F_{p+1} + F_p + F_p^{1+\frac{1}{p}}) - C_2(p) \int_0^{2\pi} (|\kappa - \overline{\kappa}|^{\frac{p}{2}})_{\sigma}^2 d\sigma.$$

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Using Sobolev inequality and Young's inequality we have

$$\partial_t F_p \le C_2(p)(F_p + F_p^\beta + F_p^{1+\frac{1}{p}}) - C_3(p)F_{3p}^{\frac{1}{3}},$$

where  $\beta = \frac{2p-1}{2p-3} > 1$  and  $C_2$ ,  $C_3$  are positive constants.

Since  $\partial_t \overline{\kappa}_g = \frac{1}{4\pi} \int (\kappa_g - \overline{\kappa}_g)^2 d\sigma$  and  $\overline{\kappa}$  is bounded above, we have  $\int_0^\infty F_2(t)dt < \infty.$ 

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Using above two inequalities, Hölder's inequality and induction, we can prove the following Lemma:

**Lemma:** For any  $p \ge 2$ ,

$$F_p(t) \to 0 \text{ as } t \to +\infty \text{ and } \int_0^\infty F_p(t)dt < \infty.$$

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Then we estimate  $\int_0^{2\pi} (\kappa_{\sigma})^2 d\sigma$  and obtain that

$$|\kappa - \bar{\kappa}||_{L^{\infty}} \to 0$$
, as  $t \to \infty$ .

# **Exponential Convergence**

To show exponential convergence:

$$\partial_t F_2 \le \left(-\frac{1}{2} + o(1)\right)F_2,$$

which implies  $F_2 \leq Ce^{-at}$  for some C, a > 0.

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which implies  $F_2 \leq Ce^{-at}$  for some C, a > 0. Then from the flow equation

$$u_t = \frac{1}{4}(\kappa - \overline{\kappa})u,$$

we can prove that u(t) converges exponentially to some  $u_{\infty}$  as  $t \to \infty$ :

$$||u(t) - u_{\infty}||_{L^{\infty}} \le Ce^{-at/2},$$

and the 1-curvature of  $g_{\infty} := u_{\infty}^{-4}g_s$  is constant 1. This completes the proof of our main Theorem.

## **Theorem** ( $\alpha = 4$ )

For  $\alpha = 4$ , we have the similar theorem:

**Theorem:** For an abstract curve  $(S^1, u_0^{-4}g_s)$ , then there is a unique smooth solution to the flow equation

$$\partial_t g = (\overline{R}_g^4 - R_g^4)g, \quad g(\theta, 0) = g_0(\theta)$$

for  $t \in [0, +\infty)$ . Moreover,  $g(t) \to g_{\infty}$  exponentially as  $t \to +\infty$ , and the 4-curvature of  $g_{\infty}$  is constant.

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Along the flow  $\overline{R}_{g}^{4}$  is always increasing,

$$\partial_t \overline{R}_g^4 = \frac{1}{4\pi} \int (R_g^4 - \overline{R}_g^4)^2 d\sigma.$$

# Upper bound for ( $\alpha = 4$ )

The upper unbound of  $\overline{R}_{q}^{4}$  follows from the following inequality:

**Proposition:** For  $u(\theta) \in H^1(S^1)$  and u > 0,

$$\int_{0}^{2\pi} \left(\frac{1}{4}u^{2} - u_{\theta}^{2}\right)d\theta \int_{0}^{2\pi} u^{-2}(\theta)d\theta \leq \pi^{2},$$

and the equality holds if and only if

$$u(\theta) = c\sqrt{\lambda^2 \cos^2 \frac{\theta - \alpha}{2} + \lambda^{-2} \sin^2 \frac{\theta - \alpha}{2}},$$

for some  $\lambda, c > 0$  and  $\alpha \in [0, 2\pi)$ .

#### **Q-curvature**

For any given g on  $S^1$  we write  $g = v^{-4/3}g_s$ , where  $g_s$  is the standard metric. We define general  $\alpha$ -Q-curvature on  $(S^1, g)$  as

$$Q_g^{\alpha} = v^{\frac{5}{3}} \left(\frac{\alpha^2}{9} v_{\theta\theta\theta\theta} + \frac{10\alpha}{9} v_{\theta\theta} + v\right),$$

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and the corresponding operator as

$$P_g^{\alpha}(f) = \frac{\alpha^2}{9} \Delta_g^2 f + \frac{10\alpha}{9} \nabla_g (R_g^{\alpha} \nabla_g f) + Q_g^{\alpha} f,$$

where  $R_g^{\alpha}$  is the  $\alpha$ -curvature of  $(S^1, g)$ .

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where  $R_g^{\alpha}$  is the  $\alpha$ -curvature of  $(S^1, g)$ .  $P_g^{\alpha}$  is a conformal covariant: if  $g_2 = \varphi^{-\frac{4}{3}}g_1$ , then  $Q_{g_2}^{\alpha} = \varphi^{\frac{5}{3}}P_{g_1}^{\alpha}\varphi$  and  $P_{g_2}^{\alpha}\psi = \varphi^{\frac{5}{3}}P_{g_1}^{\alpha}(\psi\varphi), \forall\psi.$ 

Existence of extremal metrics?

Introduce  $\alpha$ -Q-curvature flow

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In such a setting, the above flow is again a gradient flow of  $\overline{Q}_{g}^{\alpha}$ : Along the flow,  $\overline{Q}_{g}^{\alpha}$  is always decreasing:

$$\partial_t \overline{Q}_g^\alpha = -\frac{3}{4\pi} \int_{S^1} (Q_g^\alpha - \overline{Q}_g^\alpha)^2 d\sigma$$

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Again, we are interested in two cases:  $\alpha = 1$  and  $\alpha = 4$ .

Very recently, we prove the existence and convergence of the  $\alpha$ -Qcurvature flow in these two cases.

Hard part: the proof to the following inequality, which implies that  $\overline{Q_g^1}$  is bounded from below, and classifies all the extremal metrics: **Blaschke-Santaló inequality involving higher order derivative?**  $For u(\theta) \in H^2(S^1)$  and u > 0, satisfying the orthogonal condition

$$\int_{0}^{2\pi} \frac{\cos^{3}\theta}{u^{5/3}(\theta)} d\theta = \int_{0}^{2\pi} \frac{\sin^{3}\theta}{u^{5/3}(\theta)} d\theta = 0, \qquad (4)$$

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$$\int_{0}^{2\pi} (u_{\theta\theta}^{2} - 10u_{\theta}^{2} + 9u^{2}) d\theta \left(\int_{0}^{2\pi} u^{-2/3}(\theta) d\theta\right)^{3} \ge 144\pi^{4},$$

"=" holds if and only if

$$u_0(\theta) = c \left(\lambda^2 \cos^2(\theta - \beta) + \lambda^{-2} \sin^2(\theta - \beta)\right)^{\frac{3}{2}}.$$

### **Exponential convergence**

**Theorem:** Suppose the initial metric  $g_0 = v^{-\frac{4}{3}}(\theta, 0)g_s$  on  $S^1$  satisfies the orthogonal condition (4). Then there is a unique smooth solution to the flow equation

 $\partial_t \overline{g} = (\overline{Q_g^1} - Q_g^1)g, \quad g(0) = \overline{g_0}$ 

for  $t \in [0, +\infty)$ . Moreover,  $g(t) \to g_{\infty}$  exponentially as  $t \to +\infty$ , and the 1-Q-curvature of  $g_{\infty}$  is constant.

Direct computation shows that

$$Q_g^{\alpha} = \frac{\alpha}{3} \Delta_g R_g^{\alpha} + (R_g^{\alpha})^2,$$

which implies

$$\int Q_g^{\alpha} d\sigma = \int (R_g^{\alpha})^2 d\sigma.$$

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Therefore  $\int (R_g^{\alpha})^2 d\sigma$  is decreasing along the  $\alpha$ -Q-curvature flow. Thus the  $\alpha$ -Q-curvature flow can be viewed as one dimensional Calabi flow. Caution: It is not trivial to see that  $\int (R_g^{\alpha})^2 d\sigma$  is bounded below by a positive constant.

# **Applications in image processing**



# **Applications in image processing**

Top left: original image (with impulse noise).

Top right: affine image flow (10 steps).

Bottom left: affine image flow (20 steps).

Bottom right: our 4-th order image flow(10 steps).

Equation for affine flow:

 $\Phi_t = (\Phi_x^2 \Phi_{yy} + \Phi_y^2 \Phi_{xx} - 2\Phi_x \Phi_y \Phi_{xy})^{\frac{1}{3}}, \quad \Phi(0) = I(x, y).$ 

### How does it work?

Consider contour curve for any  $C \ge 0$ :

 $\Phi(x,y) = C.$ 

Move such curves simultaneously:

 $\Phi((x(t), y(t), t) = C.$ 

So

 $\Phi_x \cdot x_t + \Phi_y \cdot y_t + \Phi_t = 0,$ 

i.e.

$$\Phi_t = -(x_t, y_t) \cdot (\Phi_x, \Phi_y).$$

Let F(t) = (x(t), y(t)) represent the curve.

Curve shortening flow is defined by

$$F_t = kN = -k(\frac{\Phi_x}{|\nabla\Phi|}, \frac{\Phi_y}{|\nabla\Phi|}).$$

$\overline{}$

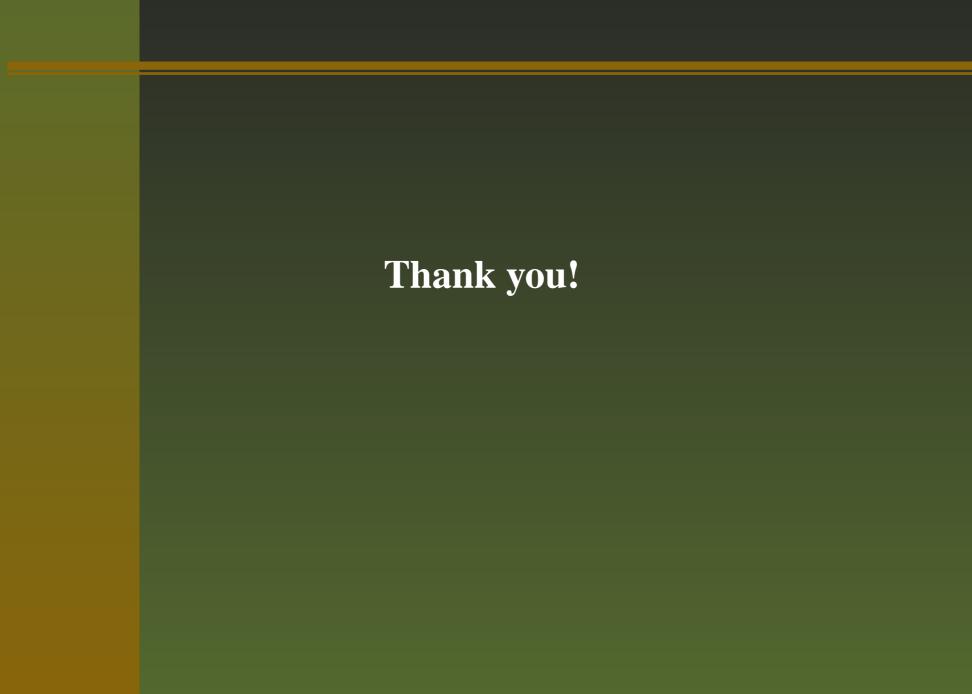
$$\Phi_t = \frac{\Phi_x^2 \Phi_{yy} + \Phi_y^2 \Phi_{xx} - 2\Phi_x \Phi_y \Phi_{xy}}{|\nabla \Phi|^2}, \quad \text{on}[0, +\infty) \times \Omega$$
  
$$\Phi(x, y, 0) = I(x, y), \quad \text{I(x, y) initial image}$$
  
various boundary condition.

# **Affine curve shortening flow**

Affine shortening flow is defined by

$$F_t = k^{1/3} N = -k^{1/3} \left( \frac{\Phi_x}{|\nabla \Phi|}, \frac{\Phi_y}{|\nabla \Phi|} \right).$$

 $\Phi_t = (\Phi_x^2 \Phi_{yy} + \Phi_y^2 \Phi_{xx} - 2\Phi_x \Phi_y \Phi_{xy})^{1/3}, \quad \text{on}[0, +\infty)$  $\Phi(x, y, 0) = I(x, y), \quad \text{I(x, y) initial image}$ various boundary condition.



For fixed length  $(\int_0^{2\pi} u^{-2} d\theta = 2\pi)$ , B-S inequality  $\Longrightarrow$ 

$$2\pi \ge \int_0^{2\pi} (u^2 - u_\theta^2) d\theta$$
$$= \int_0^{2\pi} u^3 (u + u_{\theta\theta}) u^{-2} d\theta$$
$$= \int_0^{2\pi} \kappa d\sigma.$$

 $\overline{\kappa} \leq \underline{1}.$ 

Thus:

# **Affine isoperimetric inequality**

B-S inequality 
$$\implies$$
 for  $h > 0$ ,

$$4\pi^2 \int_0^{2\pi} h(h+h_{\theta\theta}) d\theta \ge [\int_0^{2\pi} (h+h_{\theta\theta})^{\frac{2}{3}} d\theta]^3.$$

Let  $h = \langle X, -N \rangle$  be the supporting function of the closed strictly convex curve  $X(\theta)$ , then  $h + h_{\theta\theta} = 1/k$ ,  $\int_0^{2\pi} (h + h_{\theta\theta})^{\frac{2}{3}} d\theta = \int_0^{2\pi} k^{-2/3} d\theta = \sigma$ . Also  $\int_0^{2\pi} h(h + h_{\theta\theta}) d\theta = 2A$ . So

$$8\pi^2 A \ge \sigma^3.$$