

Practice Exam 3 Solutions

1.) $V = \mathbb{R}^2$ $x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$, $y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$ $\langle x, y \rangle = x_1 y_1 - x_2 y_1 - x_1 y_2 + 3x_2 y_2$
 $\langle x_1, x \rangle = x_1^2 - x_2 x_1 - x_1 x_2 + 3x_2^2 = x_1^2 - 2x_1 x_2 + 3x_2^2 = x_1^2 - 2x_1 x_2 + x_1^2 + 2x_2^2$
 $= (x_1 - x_2)^2 + 2x_2^2 \geq 0$

$$\langle x, y \rangle = x_1 y_1 - x_2 y_1 - x_1 y_2 + 3x_2 y_2 = y_1 x_1 - y_2 x_1 - y_1 x_2 + 3y_2 x_2 = \langle y, x \rangle$$

$$\langle cx, y \rangle = cx_1 y_1 - cx_2 y_1 - cx_1 y_2 + 3cx_2 y_2 = c(x_1 y_1 - x_2 y_1 - x_1 y_2 + 3x_2 y_2) = c \langle x, y \rangle$$

$$\langle x, y+z \rangle = x_1(y_1+z_1) - x_2(y_1+z_1) - x_1(y_2+z_2) + 3x_2(y_2+z_2)$$
 $= x_1 y_1 - x_2 y_1 - x_1 y_2 + 3x_2 y_2 + x_1 z_1 - x_2 z_1 - x_1 z_2 + 3x_2 z_2$
 $= \langle x, y \rangle + \langle x, z \rangle \quad \text{all four prop. satisfied so linear independent}$

2.) $V = C[-\pi, \pi]$ $\langle f, g \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(t)g(t)dt$

$$\langle f, f \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(t)^2 dt \geq 0 \quad \text{since } f(t) \geq 0$$

$$\langle f, g \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(t)g(t)dt = \frac{1}{2\pi} \int_{-\pi}^{\pi} g(t)f(t)dt = \langle g, f \rangle$$

$$\langle cf, g \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} c f(t)g(t)dt = c \frac{1}{2\pi} \int_{-\pi}^{\pi} f(t)g(t)dt = c \langle f, g \rangle$$

$$\begin{aligned} \langle f, g+h \rangle &= \frac{1}{2\pi} \int_{-\pi}^{\pi} f(t)(g(t)+h(t))dt = \frac{1}{2\pi} \int_{-\pi}^{\pi} (f(t)g(t) + f(t)h(t))dt \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} f(t)g(t)dt + \frac{1}{2\pi} \int_{-\pi}^{\pi} f(t)h(t)dt = \langle f, g \rangle + \langle f, h \rangle \end{aligned}$$

$$3.) S = \{1, t\} \quad \text{s.t. } v_1 = 1, \quad v_2 = t$$

$$u_1 = v_1, \quad \text{then } u_2 = v_2 - \text{Proj}_{u_1} v_2 = t - \frac{\langle u_1, v_2 \rangle}{\|u_1\|^2} u_1$$

$$\text{so } \langle u_1, v_2 \rangle = \int_0^1 1 \cdot t dt = \frac{t^2}{2} \Big|_0^1 = \frac{1}{2} \quad \text{so } u_2 = t - \frac{\frac{1}{2}}{1} \cdot 1 = t - \frac{1}{2}$$

$$\|u_1\|^2 = \int_0^1 1^2 dt = t \Big|_0^1 = 1$$

$$\omega_1 = \frac{u_1}{\|u_1\|} = 1, \quad \omega_2 = \frac{u_2}{\|u_2\|}, \quad \|t - \frac{1}{2}\| = \sqrt{\int_0^1 (t - \frac{1}{2})^2 dt} = \sqrt{\int_0^1 (t^2 - t + \frac{1}{4}) dt} = \sqrt{\frac{t^3}{3} - \frac{t^2}{2} + \frac{1}{4}t \Big|_0^1} = \sqrt{\frac{1}{3} - \frac{1}{2} + \frac{1}{4}} = \sqrt{\frac{1}{12}}$$

$$\text{so } \|u_2\| = \frac{1}{\sqrt{2}} = \frac{1}{2\sqrt{3}}$$

$$\text{then } \omega_1 = 1 \text{ and } \omega_2 = 2\sqrt{3}(t - \frac{1}{2})$$

$$4.) S = \{1, t, e^t\} \quad v_1 = 1, \quad v_2 = t, \quad v_3 = e^t$$

$$u_1 = v_1, \quad \text{then } u_2 = v_2 - \text{Proj}_{u_1} v_2 = t - \frac{\langle u_1, v_2 \rangle}{\|u_1\|^2} u_1 = t - \frac{1}{2} \quad \text{from last problem}$$

$$\text{then } u_3 = v_3 - \text{Proj}_{u_1} v_3 - \text{Proj}_{u_2} v_3 = e^t - \frac{\langle 1, e^t \rangle}{\|1\|^2} \cdot 1 - \frac{\langle t - \frac{1}{2}, e^t \rangle}{\|t - \frac{1}{2}\|^2} (t - \frac{1}{2})$$

$$\langle 1, e^t \rangle = \int_0^1 e^t dt = e - 1, \quad \|1\|^2 = 1$$

$$\langle t - \frac{1}{2}, e^t \rangle = \int_0^1 (t - \frac{1}{2}) e^t dt = \int_0^1 t e^t dt - \frac{1}{2} e^t \Big|_0^1 = t e^t \Big|_0^1 - \int_0^1 e^t dt - \frac{1}{2}(e - 1) \\ = e - (e - 1) - \frac{1}{2}(e - 1) = e - \frac{3}{2}(e - 1) = \frac{3}{2} - \frac{1}{2}e$$

$$\|t - \frac{1}{2}\|^2 = \frac{1}{2} \quad \text{from previous problem.}$$

$$\text{so } u_3 = e^t - (e - 1) - (\frac{3}{2} - \frac{1}{2}e)(t - \frac{1}{2}) = e^t - (\frac{3}{2} - \frac{1}{2}e)t + \frac{7}{4} - \frac{5}{4}e$$

$$\omega_1 = \frac{u_1}{\|u_1\|}, \quad \omega_2 = \frac{u_2}{\|u_2\|}, \quad \omega_3 = \frac{u_3}{\|u_3\|} \quad \|u_2\| = \frac{1}{2\sqrt{3}} \quad \text{from last problem}$$

$$\|u_3\|^2 = \int_0^1 \left(e^t - (\frac{3}{2} - \frac{1}{2}e)t + \frac{7}{4} - \frac{5}{4}e \right)^2 dt = \int_0^1 (e^t - 2et + c)^2 dt = \int_0^1 (e^{2t} - 2te^t + 2c^2 - 2ct + t^2 + c^2) dt \\ = \frac{1}{2} e^{2t} \Big|_0^1 - 2te^t \Big|_0^1 + 2c^2 \Big|_0^1 + 2c^2 \Big|_0^1 - 2ct \Big|_0^1 + \frac{t^2}{3} \Big|_0^1 + c^2 t \Big|_0^1 = \frac{1}{2}(e^2 - 1) - 26e + 26e^{-2} + 2ce - 2c - 6c + \frac{6^2}{3} + c^2 \\ = \frac{1}{2}(e^2 - 1) - 26 + 2ce - 6c + \frac{6^2}{3} + c^2 = \alpha \quad \text{so } \|u_3\| = \sqrt{\alpha}$$

$$\text{then } \omega_1 = 1, \quad \omega_2 = 2\sqrt{3}(t - \frac{1}{2}), \quad \omega_3 = \frac{1}{\sqrt{\alpha}} \left(e^t - (\frac{3}{2} - \frac{1}{2}e)t + \frac{7}{4} - \frac{5}{4}e \right)$$

$$5.) \det(I_n - AB) = \det(A(A^{-1} - B)) = \det(A)\det(A^{-1} - B)$$

$$= \det(A^{-1} - B)\det(A) = \det((A^{-1} - B)A) = \det(I_n - BA)$$

6.) recall skew-symmetric $A^t = -A$ so $\det(A^t) = \det(-A) = (-1)^n \det(A)$
 each row multiplied by -1

then $\det(A^t) = \det(A) \Rightarrow \det(A) = (-1)^n \det(A)$ if n odd then $(-1)^n = -1$

 $\Rightarrow \det(A) = -\det(A) \Rightarrow \det(A) = 0$

7.) $L: P_3 \rightarrow \mathbb{R}$ $p(t) = a_1 t^3 + a_2 t^2 + a_3 t + a_4$

so $L(p(t)) = \int_0^1 p(t) dt = \left(\frac{a_1 t^4}{4} + \frac{a_2 t^3}{3} + \frac{a_3 t^2}{2} + a_4 t \right) \Big|_0^1 = \frac{a_1}{4} + \frac{a_2}{3} + \frac{a_3}{2} + a_4$

now want $p(t)$ s.t. $L(p(t)) = 0 \Rightarrow \frac{a_1}{4} + \frac{a_2}{3} + \frac{a_3}{2} + a_4 = 0$

 $\Rightarrow a_4 = -\frac{1}{4}a_1 - \frac{1}{3}a_2 - \frac{1}{2}a_3 \quad \text{w/ } a_1, a_2, a_3 \text{ free parameters}$

so $p(t) = a_1 t^3 + a_2 t^2 + a_3 t + -\frac{1}{4}a_1 - \frac{1}{3}a_2 - \frac{1}{2}a_3 = a_1(t^3 - \frac{1}{4}) + a_2(t^2 - \frac{1}{3}) + a_3(t - \frac{1}{2})$

so basis for $\text{Ker}(L)$ is $S = \{t^3 - \frac{1}{4}, t^2 - \frac{1}{3}, t - \frac{1}{2}\}$ and $\dim \text{Ker}(L) = 3$

8.) $L: P_2 \rightarrow P_2$ $p(t) = a_1 t^2 + a_2 t + a_3$

so $L(p(t)) = t \frac{dp}{dt} = t(2a_1 t + a_2) = 2a_1 t^2 + a_2 t$

now want $p(t)$ s.t. $L(p(t)) = 0 \Rightarrow 2a_1 t^2 + a_2 t = 0$ ~~nonzero constant term~~

so ~~all terms except constant term need to be zero for all t~~

so must have $a_1 = a_2 = 0$ so basis for $\text{Ker}(L)$ is $S = \{1\}$ and $\dim \text{Ker}(L) = 1$

Alt. way is to write basis for P_2 $S = \{1, t, t^2\}$ and associated matrix A for L

$$L(1) = 0, L(t) = t, L(t^2) = 2t^2 \Rightarrow A = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \text{ clearly has dimension 1}$$

9.) Since columns of P are orthonormal then $P^t P = I_n$ so

$$\|Px\|^2 = \langle Px, Px \rangle = \langle P^t P x, x \rangle = \langle I_n x, x \rangle = \langle x, x \rangle = \|x\|^2$$

$$\therefore \|Px\| = \|x\|$$