

# Homework 5 Solution

①

$$1. a) \quad I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad A^2 = A \cdot A = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \quad A^3 = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$A^4 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad A^5 = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad A^6 = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \quad A^7 = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

...

$$\text{So } e^{tA} = I_2 + tA + \frac{t^2}{2!} A^2 + \frac{t^3}{3!} A^3 + \frac{t^4}{4!} A^4 + \dots$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \frac{t}{1!} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} + \frac{t^2}{2!} \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} + \frac{t^3}{3!} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} + \frac{t^4}{4!} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \dots$$

$$= \begin{bmatrix} 1 + 0 - \frac{t^2}{2!} + 0 + \frac{t^4}{4!} + \dots & 0 - t + 0 + \frac{t^3}{3!} + \dots \\ 0 + t + 0 - \frac{t^3}{3!} + 0 + \dots & 1 + 0 - \frac{t^2}{2!} + 0 + \frac{t^4}{4!} + \dots \end{bmatrix}$$

$$= \begin{bmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{bmatrix}$$

$$b) \quad \vec{x}(t) = e^{tA} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$\vec{x} = \begin{bmatrix} c_1 \cos t - c_2 \sin t \\ c_1 \sin t + c_2 \cos t \end{bmatrix}$$

$$\begin{aligned}
 c) \quad & \begin{cases} x_1' = -x_2 \\ x_2' = x_1 \\ x_1(0) = c_1 \\ x_2(0) = c_2 \end{cases} \implies x_2'' = x_1' \implies \begin{cases} x_2'' = -x_2 \\ x_2'' + x_2 = 0 \\ r^2 + 1 = 0, r = \pm i \end{cases} \\
 & \implies x_2 = C_2 \cos t + C_1 \sin t \\
 & \text{then } x_1 = x_2' = C_1 \cos t - C_2 \sin t
 \end{aligned}$$

$$\text{So } \vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} C_1 \cos t - C_2 \sin t \\ C_1 \sin t + C_2 \cos t \end{bmatrix}$$

so agrees with part b)

$$2. a) \quad I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$\text{So } A^k = \begin{bmatrix} 1 & k \\ 0 & 1 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

$$A^3 = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}$$

⋮

$$\begin{aligned}
 e^{tA} &= I_2 + tA + \frac{t^2}{2!} A^2 + \frac{t^3}{3!} A^3 + \dots \\
 &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} t & t \\ 0 & t \end{bmatrix} + \begin{bmatrix} t^2/2! & 2 \cdot t^2/2! \\ 0 & t^2/2! \end{bmatrix} + \begin{bmatrix} t^3/3! & 3 \cdot t^3/3! \\ 0 & t^3/3! \end{bmatrix} + \dots
 \end{aligned}$$

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$$= \begin{bmatrix} 1 + t + \frac{t^2}{2!} + \frac{t^3}{3!} + \dots & t + 2 \cdot \frac{t^2}{2!} + 3 \cdot \frac{t^3}{3!} + \dots \\ 0 & 1 + t + \frac{t^2}{2!} + \frac{t^3}{3!} + \dots \end{bmatrix}$$

$$= \begin{bmatrix} e^t & t(1 + 2 \cdot \frac{t}{2} + 3 \cdot \frac{t^2}{3!} + \dots) \\ 0 & e^t \end{bmatrix}$$

$$= \begin{bmatrix} e^t & t(1 + t + \frac{t^2}{2!} + \dots) \\ 0 & e^t \end{bmatrix} = \begin{bmatrix} e^t & te^t \\ 0 & e^t \end{bmatrix}$$

$$b) \vec{x} = e^{tA} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} e^t & te^t \\ 0 & e^t \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} c_1 e^t + c_2 te^t \\ c_2 e^t \end{bmatrix}$$

$$c) \begin{cases} x_1' = x_1 + x_2 \\ x_2' = x_2 \\ x_1(0) = c_1 \\ x_2(0) = c_2 \end{cases} \Rightarrow \begin{cases} x_2 = c_2 e^t \\ x_{1,c} = D e^t \\ x_{1,p} = A t e^t \\ x_{1,p}' = A t e^t + A e^t \\ \Rightarrow A t e^t + A e^t - A t e^t = c_2 e^t \\ \Rightarrow A = c_2 \\ \Rightarrow x_{1,p} = c_2 t e^t \\ \Rightarrow x_1 = x_{1,c} + x_{1,p} = D_1 e^t + c_2 t e^t \end{cases}$$

Need  $x_1(0) = c_1$

so  $D_1 e^0 + c_2 \cdot 0 e^0 = c_1 \Rightarrow D_1 = c_1$

$$\Rightarrow \begin{cases} x_1 = c_1 e^t + c_2 t e^t \\ x_2 = c_2 e^t \end{cases}$$

Agrees with part b).

3. a)  $A \vec{v} = \lambda \vec{v}$

$$A^2 \vec{v} = A(A \vec{v}) = A(\lambda \vec{v}) = \lambda(A \vec{v}) = \lambda(\lambda \vec{v}) = \lambda^2 \vec{v}$$

$$A^3 \vec{v} = \lambda^3 \vec{v}$$

⋮

$$\text{so } e^{tA} \vec{v} = \left( I_n + tA + \frac{t^2}{2!} A^2 + \dots \right) \vec{v}$$

$$= I_n \vec{v} + tA \vec{v} + \frac{t^2}{2!} A^2 \vec{v} + \dots$$

$$= \vec{v} + t\lambda \vec{v} + \frac{t^2 \lambda^2}{2!} \vec{v} + \dots$$

$$= \left( 1 + t\lambda + \frac{t^2 \lambda^2}{2!} + \dots \right) \vec{v} = e^{\lambda t} \vec{v}$$

b) Eigenvalue method:  $\vec{x} = e^{\lambda t} \vec{v}$  is a solution

Matrix exponential method:  $\vec{x} = e^{At} \vec{v}$  is a solution

By part a),  $\vec{x} = e^{At} \vec{v} = e^{\lambda t} \vec{v}$ .

So the two methods produce the same solution.

c) By eigenvalue method, general solution is

$$\vec{x} = c_1 e^{\lambda_1 t} \vec{v}_1 + \dots + c_n e^{\lambda_n t} \vec{v}_n$$

$$\text{(notice } \vec{x}(0) = c_1 \vec{v}_1 + \dots + c_n \vec{v}_n = \vec{v} \text{)}$$

By matrix exponential method, general solution is

$$\vec{x} = e^{At} \vec{v}$$

since  $\vec{v} = c_1 \vec{v}_1 + \dots + c_n \vec{v}_n$ , this is

$$e^{At} \vec{v} = e^{At} (c_1 \vec{v}_1 + \dots + c_n \vec{v}_n)$$

$$= c_1 e^{At} \vec{v}_1 + \dots + c_n e^{At} \vec{v}_n$$

$$= c_1 e^{\lambda_1 t} \vec{v}_1 + \dots + c_n e^{\lambda_n t} \vec{v}_n$$

So the two methods produce the same solution.