

April 28, 2010

Instructions: Give concise answers, but clearly indicate your reasoning. Most of the problems have rather short answers, so if you find yourself involved in a lengthy calculation, it might be a good idea to move on and come back to that problem if you have time.

I. Let A be the matrix

(6)

$$\begin{bmatrix} t & -2 & 0 & 3 \\ 0 & 3 & 1 & 2 \\ 0 & t & 0 & 2 \\ t & 0 & 3 & 4 \end{bmatrix}.$$

- (a) Calculate $\det(A)$ as follows. First do an elementary row operation to make the $(4, 1)$ -entry equal to 0, then do cofactor expansion down the first column to reduce to computing the determinant of a 3×3 matrix. On that 3×3 matrix, do an elementary row operation that creates a second 0 in the middle column, and continue from there.

Performing $R_4 - R_1 \rightarrow R_4$, we obtain the matrix

$$\begin{bmatrix} t & -2 & 0 & 3 \\ 0 & 3 & 1 & 2 \\ 0 & t & 0 & 2 \\ 0 & 2 & 3 & 1 \end{bmatrix}.$$

Now expand down the first column, and continue:

$$\begin{vmatrix} t & -2 & 0 & 3 \\ 0 & 3 & 1 & 2 \\ 0 & t & 0 & 2 \\ 0 & 2 & 3 & 1 \end{vmatrix} = t \begin{vmatrix} 3 & 1 & 2 \\ t & 0 & 2 \\ 2 & 3 & 1 \end{vmatrix} = t \begin{vmatrix} 3 & 1 & 2 \\ t & 0 & 2 \\ -7 & 0 & -5 \end{vmatrix} = -t \begin{vmatrix} t & 2 \\ -7 & -5 \end{vmatrix} = -t(-5t + 14) = 5t^2 - 14t$$

- (b) Using your expression for $\det(A)$, find the values of t for which A is singular.

Solving $0 = \det(A) = 5t^2 - 14t = t(5t - 14)$ gives the values $t = 0$ and $t = 14/5$.

II. Let $L: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear transformation defined by
(10)

$$L \left(\begin{bmatrix} a \\ b \\ c \end{bmatrix} \right) = \begin{bmatrix} a + 2b \\ a - b - c \\ 3a - 2c \end{bmatrix}.$$

(You do not need to verify that L is linear.) As you know, the standard matrix representation of L is

$$A = \begin{bmatrix} 1 & 2 & 0 \\ 1 & -1 & -1 \\ 3 & 0 & -2 \end{bmatrix}.$$

(a) Use the standard matrix representation to find a basis for the kernel of L .

The kernel is the null space of A , that is, the space of solutions of $AX = 0$. We find it using elementary row operations:

$$A \rightarrow \begin{bmatrix} 1 & 2 & 0 \\ 0 & -3 & -1 \\ 0 & -6 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 1/3 \\ 0 & 0 & 0 \end{bmatrix}$$

so the null space is $\begin{bmatrix} 2r/3 \\ -r/3 \\ r \end{bmatrix}$ and possible bases include $\left\{ \begin{bmatrix} 2/3 \\ -1/3 \\ 1 \end{bmatrix} \right\}$ or $\left\{ \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix} \right\}$.

(b) Use the standard matrix representation to find a basis for the range of L .

The range of L is the column space of A , which we find using elementary column operations:

$$A \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 1 & -3 & -1 \\ 3 & -6 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 3 & 2 & 0 \end{bmatrix}$$

and a basis is $\left\{ \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \right\}$

- III.** (a) Let A be an $n \times m$ matrix, and let $L: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be the matrix transformation defined by $L(v) = Av$.
 (8) Verify that L is linear.

$$L(av + bw) = A(av + bw) = A(av) + A(bw) = aAv + bAw = aL(v) + bL(w).$$

- (b) Let P_3 be the space of polynomials of degree at most 3, and let $L: P_3 \rightarrow P_3$ be the function defined by $L(p(t)) = p(t) + t$. By giving a specific counterexample, show that L is not linear.

$$L(t + t) = t + t + t = 3t, \text{ but } L(t) + L(t) = (t + t) + (t + t) = 4t.$$

- IV.** Let P_2 be the space of polynomials of degree at most 2, and let S be the ordered basis $\{t^2 - t + 1, t - 1, t^2 + 1\}$ of P_2 .
 (10)

- (a) If the S -coordinate vector of the polynomial p is $p_S = \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix}$, find p .

$$p = -(t^2 - t + 1) + 2(t - 1) - (t^2 + 1) = -2t^2 + 3t - 4.$$

- (b) Find the S -coordinate vector of the polynomial $t^2 + t - 1$.

We solve

$$t^2 + t - 1 = a(t^2 - t + 1) + b(t - 1) + c(t^2 + 1) = (a + c)t^2 + (-a + b)t + (a - b + c)$$

$$\begin{bmatrix} 1 & 0 & 1 & 1 \\ -1 & 1 & 0 & 1 \\ 1 & -1 & 1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 \\ -1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\text{so } (a, b, c) = (1, 2, 0) \text{ and } (t^2 + t - 1)_S = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}.$$

$$\text{Check: } (t^2 - t + 1) + 2(t - 1) = t^2 + t - 1.$$

- (c) Let T be the basis $\{t^2, t, 1\}$ of P_2 . Find the transition matrix (also called the change-of-basis matrix) $P_{T \leftarrow S}$ from S -coordinates to T -coordinates.

The columns of $P_{T \leftarrow S}$ are $(t^2 - t + 1)_T$, $(t - 1)_T$, and $(t^2 + 1)_T$, so

$$P_{T \leftarrow S} = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{bmatrix}$$

V. Let P be a nonsingular $n \times n$ matrix.

(6)
(a) Verify that $\det(P^{-1}) = 1/\det(P)$.

We have $1 = \det(I_n) = \det(PP^{-1}) = \det(P)\det(P^{-1})$, so $\det(P^{-1}) = 1/\det(P)$.

(b) Use part (a) to verify that if A is any $n \times n$ matrix, then $\det(P^{-1}AP) = \det(A)$.

$\det(P^{-1}AP) = \det(P^{-1})\det(A)\det(P) = (1/\det(P))\det(A)\det(P) = \det(A)$.

VI. Let $A = ([a_{i,j}])$ be a 4×4 matrix, and consider the formula

(4)

$$\det(A) = \sum (\pm) a_{1,\sigma(1)} a_{2,\sigma(2)} a_{3,\sigma(3)} a_{4,\sigma(4)} .$$

Determine the sign (i. e. tell whether the term has a plus or a minus sign in the formula) of the term that contains $a_{1,2}a_{2,3}a_{3,4}a_{4,1}$ (make your reasoning clear— answers of “plus” or “minus” without a correct explanation won’t receive any credit).

The permutation 2341 has $1 + 1 + 1 = 3$ inversions, so is odd, so the term that contains $a_{1,2}a_{2,3}a_{3,4}a_{4,1}$ has a minus sign.

VII. Let V be a vector space of dimension 3, and let $T = \{t_1, t_2, t_3\}$ be an ordered basis of V . Let $L: V \rightarrow V$ be the linear transformation whose matrix representation with respect to T -coordinates on the domain and

the codomain is $A = \begin{bmatrix} 0 & -2 & 1 \\ 1 & 2 & 1 \\ 0 & 2 & 0 \end{bmatrix}$. Write $L(2t_1 + t_2 - t_3)$ as a linear combination of t_1 , t_2 , and t_3 .

$$(L(2t_1 + t_2 - t_3))_T = A (2t_1 + t_2 - t_3)_T = A \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -3 \\ 3 \\ 2 \end{bmatrix}, \text{ so } L(2t_1 + t_2 - t_3) = -3t_1 + 3t_2 + 2t_3.$$

VIII. An $n \times n$ matrix B is obtained from a matrix $A = [a_{i,j}]$ by the elementary row operation $kR_i \rightarrow R_i$. Use (4) the formula for $\det(A)$ to explain why $\det(B) = k \det(A)$.

The formula for the determinant gives

$$\begin{aligned} \det(B) &= \sum (\pm) a_{1,\sigma(1)} a_{2,\sigma(2)} \cdots (ka_{i,\sigma(i)}) \cdots a_{n,\sigma(n)} = \sum (\pm) k a_{1,\sigma(1)} a_{2,\sigma(2)} \cdots a_{i,\sigma(i)} \cdots a_{n,\sigma(n)} \\ &= k \sum (\pm) a_{1,\sigma(1)} a_{2,\sigma(2)} \cdots a_{i,\sigma(i)} \cdots a_{n,\sigma(n)} = k \det(A) . \end{aligned}$$