

For all problems involving \mathbb{R}^n , you may assume the inner product is the dot product unless otherwise specified.

$$1. \text{ Let } S = \left\{ \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}, \begin{bmatrix} 1/2 \\ -1/2 \\ 1/2 \\ -1/2 \end{bmatrix}, \begin{bmatrix} 1/2 \\ -1/2 \\ -1/2 \\ 1/2 \end{bmatrix} \right\}.$$

Verify that S is an orthonormal basis for \mathbb{R}^4 . Let $\mathbf{v} = \begin{bmatrix} 4 \\ -1 \\ 2 \\ 7 \end{bmatrix}$. Use dot products

to find $[\mathbf{v}]_S$.

All pairs of distinct vectors have dot product 0 (there are 6 pairs to check) and all vectors in S have length 1, so S is orthonormal. It is linearly independent because it is orthogonal. S is a linearly independent set of 4 vectors in a 4-dimensional vector space so it is a basis. To find $[\mathbf{v}]_S$, write $\mathbf{v} = a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + a_3\mathbf{v}_3 + a_4\mathbf{v}_4$ where $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4$ are the vectors in S . As S is orthonormal, $a_i = \mathbf{v}_i \cdot \mathbf{v}$. So we can compute the a_i by taking 4 dot products.

$$a_1 = \mathbf{v}_1 \cdot \mathbf{v} = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ -1 \\ 2 \\ 7 \end{bmatrix} = 3/\sqrt{2}$$

$$a_2 = \mathbf{v}_2 \cdot \mathbf{v} = \begin{bmatrix} 0 \\ 0 \\ 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \cdot \begin{bmatrix} 4 \\ -1 \\ 2 \\ 7 \end{bmatrix} = 9/\sqrt{2}$$

$$a_3 = \mathbf{v}_3 \cdot \mathbf{v} = \begin{bmatrix} 1/2 \\ -1/2 \\ 1/2 \\ -1/2 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ -1 \\ 2 \\ 7 \end{bmatrix} = 0$$

$$a_4 = \mathbf{v}_4 \cdot \mathbf{v} = \begin{bmatrix} 1/2 \\ -1/2 \\ -1/2 \\ 1/2 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ -1 \\ 2 \\ 7 \end{bmatrix} = 5$$

$$\text{So } [\mathbf{v}]_S = \begin{bmatrix} 3/\sqrt{2} \\ 9/\sqrt{2} \\ 0 \\ 5 \end{bmatrix}.$$

2. Let $S = \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \right\}$. S is a basis for \mathbb{R}^3 . Use the Gram-Schmidt process to transform S into:

(a) an orthogonal basis.

Let $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix}$. The new basis will be $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$.

Take $\mathbf{v}_1 = \mathbf{u}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$.

Then $\mathbf{v}_2 = -\frac{\mathbf{v}_1 \cdot \mathbf{u}_2}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 + \mathbf{u}_2 = -\frac{2}{2} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.

Then $\mathbf{v}_3 = -\frac{\mathbf{v}_1 \cdot \mathbf{u}_3}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{v}_2 \cdot \mathbf{u}_3}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 + \mathbf{u}_3 = -\frac{(-1)}{2} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} - \frac{6}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 1 \\ -1/2 \end{bmatrix}$.

The orthogonal basis you get is $\left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1/2 \\ 1 \\ -1/2 \end{bmatrix} \right\}$. You can also replace \mathbf{v}_3 with $2\mathbf{v}_3$ and it will still be an orthogonal basis and there won't be any fractions. The resulting basis is $\left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix} \right\}$.

(b) an orthonormal basis.

Take the basis from (a) and divide each vector by its length. The resulting orthonormal basis is $\left\{ \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ -1/\sqrt{2} \end{bmatrix}, \begin{bmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}, \begin{bmatrix} -1/\sqrt{6} \\ 2/\sqrt{6} \\ -1/\sqrt{6} \end{bmatrix} \right\}$.

3. Use the Gram-Schmidt process to find an orthonormal basis for W where W is the subspace of \mathbb{R}^4 which consists of all vectors of the form $\begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix}$ such that $a + b + c + d = 0$.

The answer to this problem depends on the basis you pick for W . One possibility is to solve for d so $d = -a - b - c$ then rewrite $\begin{bmatrix} a \\ b \\ c \\ -a - b - c \end{bmatrix}$ as

$$a \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix} + c \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix}. \text{ The basis is then } \mathbf{u}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}, \mathbf{u}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix}. \text{ Then } \mathbf{v}_1 = \mathbf{u}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}.$$

$$\text{Then } \mathbf{v}_2 = -\frac{\mathbf{v}_1 \cdot \mathbf{u}_2}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 + \mathbf{u}_2 = -\frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 1 \\ 0 \\ -1/2 \end{bmatrix}. \text{ To avoid fractions,}$$

$$\text{we can replace } \mathbf{v}_2 \text{ with } 2\mathbf{v}_2, \text{ so instead take } \mathbf{v}_2 = \begin{bmatrix} -1 \\ 2 \\ 0 \\ -1 \end{bmatrix}$$

$$\text{. Then } \mathbf{v}_3 = -\frac{\mathbf{v}_1 \cdot \mathbf{u}_3}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{v}_2 \cdot \mathbf{u}_3}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 + \mathbf{u}_3 = -\frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix} - \frac{1}{6} \begin{bmatrix} -1 \\ 2 \\ 0 \\ -1 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1/3 \\ -1/3 \\ 1 \\ -1/3 \end{bmatrix}.$$

$$\text{To avoid fractions, we can replace } \mathbf{v}_3 \text{ with } 3\mathbf{v}_3 \text{ so } \mathbf{v}_3 = \begin{bmatrix} -1 \\ -1 \\ 3 \\ -1 \end{bmatrix}.$$

The orthogonal basis you get is $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 3 \\ -1 \end{bmatrix} \right\}$. To get an orthonormal basis, divide each vector by its length.

$$\text{The resulting basis is } \left\{ \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ 0 \\ -1/\sqrt{2} \end{bmatrix}, \begin{bmatrix} -1/\sqrt{6} \\ 2\sqrt{6} \\ 0 \\ -1\sqrt{6} \end{bmatrix}, \begin{bmatrix} -1/\sqrt{12} \\ -1/\sqrt{12} \\ 3/\sqrt{12} \\ -1/\sqrt{12} \end{bmatrix} \right\}.$$

Note: If you started by solving for a instead of d , the original basis would

be $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ and the orthogonal matrix resulting from Gram-Schmidt would be $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ -1 \\ 3 \end{bmatrix} \right\}$. The resulting orthonormal basis would then be $\left\{ \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1/\sqrt{6} \\ -1/\sqrt{6} \\ 2/\sqrt{6} \\ 0 \end{bmatrix}, \begin{bmatrix} -1/\sqrt{12} \\ -1/\sqrt{12} \\ -1/\sqrt{12} \\ 3/\sqrt{12} \end{bmatrix} \right\}$.

4. Let V be P_2 with inner product $(p(t), q(t)) = \int_0^1 p(t)q(t) dt$. Use the Gram-Schmidt process to transform the basis $\{1, t, t^2\}$ into an orthogonal basis.

Let $\mathbf{u}_1 = 1, \mathbf{u}_2 = t, \mathbf{u}_3 = t^2$. Take $\mathbf{v}_1 = \mathbf{u}_1 = 1$. Then $\mathbf{v}_2 = -\frac{(\mathbf{v}_1, \mathbf{u}_2)}{(\mathbf{v}_1, \mathbf{v}_1)}\mathbf{v}_1 + \mathbf{u}_2$. The inner products are $(\mathbf{v}_1, \mathbf{u}_2) = (1, t) = \int_0^1 (1)(t) dt = 1/2$ and $(\mathbf{v}_1, \mathbf{v}_1) = (1, 1) = \int_0^1 (1)(1) dt = 1$. Plugging these in we get that $\mathbf{v}_2 = -\frac{(1/2)}{1}1 + t = t - \frac{1}{2}$. If we want to avoid fractions, we can replace this with $2t - 1$ so $\mathbf{v}_2 = 2t - 1$. Then $\mathbf{v}_3 = -\frac{(\mathbf{v}_1, \mathbf{u}_3)}{(\mathbf{v}_1, \mathbf{v}_1)}\mathbf{v}_1 - \frac{(\mathbf{v}_2, \mathbf{u}_3)}{(\mathbf{v}_2, \mathbf{v}_2)}\mathbf{v}_2 + \mathbf{u}_3$. The inner products are $(\mathbf{v}_1, \mathbf{u}_3) = (1, t^2) = \int_0^1 (1)(t^2) dt = 1/3$, $(\mathbf{v}_1, \mathbf{v}_1) = 1$, $(\mathbf{v}_2, \mathbf{u}_3) = (2t - 1, t^2) = \int_0^1 (2t - 1)(t^2) dt = \int_0^1 2t^3 - t^2 dt = \frac{1}{2} - \frac{1}{3} = 1/6$, and $(\mathbf{v}_2, \mathbf{v}_2) = (2t - 1, 2t - 1) = \int_0^1 (2t - 1)^2 dt = \int_0^1 4t^2 - 4t + 1 dt = \frac{4}{3} - 2 + 1 = \frac{1}{3}$. Plugging these in we get $\mathbf{v}_3 = -\frac{(1/3)}{1}1 - \frac{(1/6)}{(1/3)}(2t - 1) + t^2 = t^2 - t + \frac{1}{6}$, or to avoid fractions, $6t^2 - 6t + 1$.

The orthogonal basis is $\{1, 2t - 1, 6t^2 - 6t + 1\}$.

5. Let W be the subspace of \mathbb{R}^3 spanned by $\left\{ \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 7 \end{bmatrix} \right\}$.

(a) Find a basis for W^\perp .

The is the set of all vectors $\begin{bmatrix} a \\ b \\ c \end{bmatrix}$ which are perpendicular to all vectors in W . Note that if a vector is perpendicular a set of vectors, then it is perpendicular to all the linear combinations of those vectors. It follows that we just need to find the vectors $\begin{bmatrix} a \\ b \\ c \end{bmatrix}$ which are perpendic-

ular to the three spanning vectors. If we take dot products, we get that $0 = \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = a + 2b + 4c$, $0 = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = -a + 2b$,

$0 = \begin{bmatrix} 3 \\ 1 \\ 7 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = 3a + b + 7c$. We are therefore looking for all solutions to the

homogeneous linear system $a + 2b + 4c = 0$, $-a + 2b = 0$, $3a + b + 7c = 0$.

This has coefficient matrix $\begin{bmatrix} 1 & 2 & 4 \\ -1 & 2 & 0 \\ 3 & 1 & 7 \end{bmatrix}$. The RREF of this matrix is

$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$. Then c can be anything, $b = -c$, $a = -2c$ so the solution are

all vectors of the form $\begin{bmatrix} -2c \\ -c \\ c \end{bmatrix}$.

W^\perp is the set of all vectors of the form $\begin{bmatrix} -2c \\ -c \\ c \end{bmatrix}$. These are all the multiples

of $\begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix}$ so $\left\{ \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} \right\}$ is a basis for W^\perp .

(b) Find $\dim W$ and $\dim W^\perp$.

By the pervious part, $\dim W^\perp = 1$ since a basis for W^\perp has size 1. Then $\dim W + \dim W^\perp = \dim \mathbf{R}^3$ so $\dim W = 2$. Note that the given spanning set for W is not linearly independent as the last vector is a linear combination of the first two.

(c) Describe W and W^\perp geometrically.

W is a 2 dimensional subspace of \mathbf{R}^3 so it is a plane through the origin. W^\perp is a one dimensional subspace of \mathbf{R}^3 so it is a line through the origin. Note that the line W^\perp is normal to the plane W .

6. Let $A = \begin{bmatrix} 1 & 0 & 3 & 1 & 0 \\ 0 & 1 & 0 & -1 & 2 \\ 2 & 1 & 6 & 1 & 2 \\ 0 & 0 & 1 & 0 & -3 \end{bmatrix}$. Let U be the null space of A and W be the column space of A^T . Note that U and W are both subspaces of \mathbf{R}^5 .

(a) Find a basis for U .

The RREF of A is $\begin{bmatrix} 1 & 0 & 0 & 1 & 9 \\ 0 & 1 & 0 & -1 & 2 \\ 0 & 0 & 1 & 0 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$. If we use variables x, y, z, r, s then r, s are anything and $z = 3s, y = r - 2s, x = -r - 9s$. The null space is all vectors of the form $\begin{bmatrix} -r - 9s \\ r - 2s \\ 3s \\ r \\ s \end{bmatrix} = r \begin{bmatrix} -1 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} -9 \\ -2 \\ 3 \\ 0 \\ 1 \end{bmatrix}$. A basis for the null space is $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -9 \\ -2 \\ 3 \\ 0 \\ 1 \end{bmatrix} \right\}$.

(b) Find a basis for W .

From the RREF of A , a basis for the row space of A is $\{[1 \ 0 \ 0 \ 1 \ 9], [0 \ 1 \ 0 \ -1 \ 2], [0 \ 0 \ 1 \ 0 \ -3]\}$ so a basis for the column space of A^T will be $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 9 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ -3 \end{bmatrix} \right\}$.

Another possible method to find a basis for the column space of A^T is to find RREF of A^T then take the columns of A^T that correspond to columns in RREF with leading ones. The basis you get from this method

is $\left\{ \begin{bmatrix} 1 \\ 0 \\ 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ -3 \end{bmatrix} \right\}$.

(c) Show that if \mathbf{u} is in U and \mathbf{w} is in W then $\mathbf{u} \cdot \mathbf{w} = 0$.

If \mathbf{u} is in U then $\mathbf{u} = \begin{bmatrix} -r - 9s \\ r - 2s \\ 3s \\ r \\ s \end{bmatrix}$ for some r, s . If \mathbf{w} is in W then $\mathbf{w} =$

$$\begin{bmatrix} x \\ y \\ z \\ x - y \\ 9x + 2y - 3z \end{bmatrix}$$
 for some x, y, z . Note that we are using the first basis

found in part (b), it will also work to use the second basis. Then $\mathbf{u} \cdot \mathbf{w} =$

$$\begin{bmatrix} -r - 9s \\ r - 2s \\ 3s \\ r \\ s \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ x - y \\ 9x + 2y - 3z \end{bmatrix} = (-r - 9s)(x) + (r - 2s)(y) + (3s)(z) + (r)(x - y) + (s)(9x + 2y - 3z) = -rx - 9sx + ry - 2sy + 3sz + rx - ry + 9xs + 2sy - 3sz = 0.$$

7. Let V be a finite dimensional inner product space and let W be a subspace of V . Find $\dim W^\perp$ if:

(a) $\dim V = 7$ and $\dim W = 3$.

$$\dim W^\perp = \dim V - \dim W = 7 - 3 = 4.$$

(b) $V = \mathbb{R}^2$ and W is a line through the origin.

$$\dim W^\perp = \dim V - \dim W = 2 - 1 = 1.$$

(c) $V = \mathbb{R}^3$ and W is a line through the origin.

$$\dim W^\perp = \dim V - \dim W = 3 - 1 = 2.$$