## MATH 3333

# Midterm III November 15, 2007

### Name :

### **I.D. no.** :

- Calculators are not allowed. The problems are set so that you should not need calculators at all.
- Show as much work as possible. Answers without explanation will not receive any credit.
- Best of Luck.

i) (20 **Points**) Let  $L: \mathbb{R}^4 \to \mathbb{R}^3$  be the function defined by

$$L\begin{pmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{bmatrix}) = \begin{bmatrix} u_3 + u_2 \\ u_4 - u_1 + 2u_2 \\ u_3 \end{bmatrix}$$

a) Show that L is a linear transformation.

$$\begin{split} L\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix} + \begin{bmatrix} v_1\\ v_2\\ v_3\\ v_4 \end{bmatrix}) &= L\begin{pmatrix} \begin{bmatrix} u_1+v_1\\ u_2+v_2\\ u_3+v_3\\ u_4+v_4 \end{bmatrix}) = \begin{bmatrix} (u_3+v_3)+(u_2+v_2)\\ (u_4+v_4)-(u_1+v_1)+2(u_2+v_2)\\ u_3+v_3 \end{bmatrix} \\ &= \begin{bmatrix} (u_3+u_2)+(v_3+v_2)\\ (u_4-u_1+2u_2)+(v_4-v_1+2v_2)\\ u_3+v_3 \end{bmatrix} = \begin{bmatrix} u_3+u_2\\ u_4-u_1+2u_2\\ u_3 \end{bmatrix} + \begin{bmatrix} v_3+v_2\\ v_4-v_1+2v_2\\ v_3 \end{bmatrix} \\ &= L\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) + L\begin{pmatrix} \begin{bmatrix} v_1\\ v_2\\ v_3\\ v_4 \end{bmatrix}) \\ &= L\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) = L\begin{pmatrix} \begin{bmatrix} cu_1\\ cu_2\\ cu_3\\ cu_4 \end{bmatrix}) = \begin{bmatrix} cu_3+cu_2\\ cu_3+cu_2\\ cu_3 \end{bmatrix} = c\begin{bmatrix} u_3+u_2\\ u_3+u_2\\ u_3 \end{bmatrix} = cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= L\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) = L\begin{pmatrix} \begin{bmatrix} cu_1\\ cu_2\\ cu_3\\ cu_3 \end{bmatrix} = c\begin{bmatrix} cu_3+cu_2\\ u_3 \end{bmatrix} \\ &= c\begin{bmatrix} u_3+u_2\\ u_3+u_2\\ u_3 \end{bmatrix} = cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4 \end{bmatrix}) \\ &= cL\begin{pmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3 \end{bmatrix}) \\ &= cL\begin{pmatrix} u_1\\ u_2\\ u_3 \end{bmatrix} \\ &= cL\begin{pmatrix} u_1$$

Hence L is a linear transformation.

b) Find the standard matrix representing L.

$$L(e_1) = L\begin{pmatrix} 1\\0\\0\\0 \end{pmatrix} = \begin{bmatrix} 0\\-1\\0 \end{bmatrix}, \quad L(e_2) = L\begin{pmatrix} 0\\1\\0\\0 \end{bmatrix} = \begin{bmatrix} 1\\2\\0 \end{bmatrix},$$
$$L(e_3) = L\begin{pmatrix} 0\\0\\1\\0 \end{bmatrix} = \begin{bmatrix} 1\\0\\1\\0 \end{bmatrix}, \quad L(e_4) = L\begin{pmatrix} 0\\0\\0\\1\\1 \end{bmatrix} = \begin{bmatrix} 0\\1\\0\\1 \end{bmatrix}.$$

Hence the standard matric representing L is

$$\begin{bmatrix} 0 & 1 & 1 & 0 \\ -1 & 2 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}.$$

ii) (20 **Points**) Let 
$$A = \begin{bmatrix} 1 & -1 & 2 \\ 2 & 6 & -8 \\ 5 & 3 & -2 \end{bmatrix}$$
. Verify the formula  
 $Rank(A) + Nullity(A) = 3$ 

The reduced row echelon form of A is given by the matrix

$$B = \begin{bmatrix} 1 & 0 & 1/2 \\ 0 & 1 & -3/2 \\ 0 & 0 & 0 \end{bmatrix}.$$

Since the row space of A is the same as the row space of B we see that

$$Rank(A) = 2.$$

To obtain nullity (= dimension of null space) we have to find the null space of A, which means that we have to solve the system  $A\mathbf{x} = 0$ . The reduced row echelon form of the augmented matrix is

$$\left(\begin{array}{rrrrr} 1 & 0 & 1/2 & 0\\ 0 & 1 & -3/2 & 0\\ 0 & 0 & 0 & 0 \end{array}\right).$$

Hence we get

$$x_1 + \frac{1}{2}x_3 = 0$$
 and  $x_2 - \frac{3}{2}x_3 = 0$ .

Setting  $x_3 = r$ , any real number, we get  $x_1 = -1/2r$ ,  $x_2 = 3/2r$ . So the null space of A is given by all vectors of the form

$$\begin{bmatrix} -1/2r \\ 3/2r \\ r \end{bmatrix} = r \begin{bmatrix} -1/2 \\ 3/2 \\ 1 \end{bmatrix} \Rightarrow \text{ Basis for Null space of } A = \{ \begin{bmatrix} -1/2 \\ 3/2 \\ 1 \end{bmatrix} \} \Rightarrow Nullity(A) = 1.$$

Hence

$$Rank(A) + Nullity(A) = 2 + 1 = 3.$$

Note : Nullity of A is not necessarily the number of zero rows in the reduced row echelon form of a matrix. For example the matrix  $\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$  has only one zero row but its nullity is 4.

iii) (20 **Points**) Find the basis for and dimension of the subspace W of  $R_3$  spanned by

$$S = \{ \begin{bmatrix} -1 & -3 & 4 \end{bmatrix}, \begin{bmatrix} 1 & 4 & -6 \end{bmatrix}, \begin{bmatrix} -1 & 1 & -4 \end{bmatrix}, \begin{bmatrix} 0 & 1 & -2 \end{bmatrix} \}$$

Step 1 : Consider

$$a_1 \begin{bmatrix} -1 & -3 & 4 \end{bmatrix} + a_2 \begin{bmatrix} 1 & 4 & -6 \end{bmatrix} + a_3 \begin{bmatrix} -1 & 1 & -4 \end{bmatrix} + a_4 \begin{bmatrix} 0 & 1 & -2 \end{bmatrix} = \mathbf{0}$$

This gives us the system of linear equations

$$-a_1 + a_2 - a_3 = 0$$
  
$$-3a_1 + 4a_2 + a_3 + a_4 = 0$$
  
$$4a_1 - 6a_2 - 4a_3 - 2a_4 = 0$$

Step 2 : The augmented matrix for the above system is

$$A = \begin{pmatrix} -1 & 1 & -1 & 0 & | & 0 \\ -3 & 4 & 1 & 1 & | & 0 \\ 4 & -6 & -4 & -2 & | & 0 \end{pmatrix}$$

and the corresponding reduced row echelon form is given by

$$B = \left(\begin{array}{rrrrr} 1 & 0 & 5 & 1 & | & 0 \\ 0 & 1 & 4 & 1 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{array}\right)$$

**Step 3 :** Since the leading 1's are in the first and second column, the basis for W is given by  $\{\begin{bmatrix} -1 & -3 & 4 \end{bmatrix}, \begin{bmatrix} 1 & 4 & -6 \end{bmatrix}\}$  and hence dim(W) = 2.

Alternatively, you could consider the matrix

$$C = \begin{bmatrix} -1 & -3 & 4\\ 1 & 4 & -6\\ -1 & 1 & -4\\ 0 & 1 & -2 \end{bmatrix}$$

whose reduced row echelon form is given by

$$D = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Since W is the same as the row space of C which is the same as the row space of D we get that basis for W is  $\{\begin{bmatrix} 1 & 0 & 2 \end{bmatrix}, \begin{bmatrix} 0 & 1 & -2 \end{bmatrix}\}$  and hence  $\dim(W) = 2$ .

iv) (20 **Points**) Let  $L: P_2 \to P_3$  be the function defined by

$$L(p(t)) = (t^{2} + 1)p'(t).$$

(Here p'(t) stands for derivative)

a) Show that L is a linear transformation.

$$L(p_1(t) + p_2(t)) = (t^2 + 1)(p_1(t) + p_2(t))' = (t^2 + 1)(p'_1(t) + p'_2(t))$$
  
=  $(t^2 + 1)p'_1(t) + (t^2 + 1)p'_2(t) = L(p_1(t)) + L(p_2(t))$   
$$L(cp(t)) = (t^2 + 1)(cp(t))' = (t^2 + 1)(cp'(t)) = c(t^2 + 1)p'(t) = cL(p(t))$$

Hence L is a linear transformation.

b) Find a basis for Ker(L).

A vector p(t) lies in Ker(L) if

$$L(p(t)) = 0 \Rightarrow (t^2 + 1)p'(t) = 0 \Rightarrow p'(t) = 0 \Rightarrow p(t) = c$$

We get the last condition by integrating p'(t) = 0. Hence the basis for Ker(L) is  $\{1\}$ .

c) Find dim Ker(L).

Since there is one vector in the basis of Ker(L) we have dim Ker(L) = 1.

#### v) (20 **Points**)

a) Recall that a linear transformation  $L: V \to W$  is called one-to-one if it satisfies the condition  $L(\mathbf{v}_1) = L(\mathbf{v}_2) \Rightarrow \mathbf{v}_1 = \mathbf{v}_2$ . Show that if  $Ker(L) = \{\mathbf{0}\}$ , then L is one-to-one.

We have

$$L(\mathbf{v}_1) = L(\mathbf{v}_2) \Rightarrow L(\mathbf{v}_1) - L(\mathbf{v}_2) = \mathbf{0} \Rightarrow L(\mathbf{v}_1 - \mathbf{v}_2) = \mathbf{0}$$
  
( because *L* is a linear transformation )  
$$\Rightarrow \mathbf{v}_1 - \mathbf{v}_2 \text{ lies in } Ker(L) \quad ( \text{ by defn of Kernel } )$$
  
$$\Rightarrow \mathbf{v}_1 - \mathbf{v}_2 = \mathbf{0} \quad ( \text{ Since } Ker(L) = \{\mathbf{0}\})$$
  
$$\Rightarrow \mathbf{v}_1 = \mathbf{v}_2.$$

Hence we have shown that if  $Ker(L) = \{0\}$  then we get the condition  $L(\mathbf{v}_1) = L(\mathbf{v}_2) \Rightarrow \mathbf{v}_1 = \mathbf{v}_2$ , which implies that L is one-to-one.

b) For any  $m \times n$  matrix A show that

$$RankA = RankA^T$$

We have

Rank(A) = RowRank(A) = dimension of row space of A= dimension of column space of  $A^{T}$ ( since the rows of A are the same as the columns of  $A^{T}$ ) =  $ColumnRank(A^{T}) = Rank(A^{T})$ 

Hence we get  $RankA = RankA^T$ , as required.